

## F-18 Stereo Vision Data collection

Completed Technology Project (2017 - 2018)



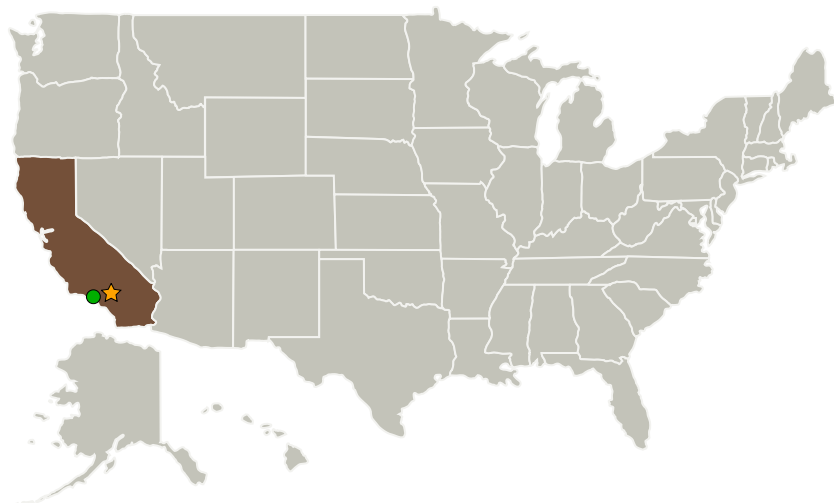
## Project Introduction

Integration onto an F-18 of JPL's collaborative stereo technology for robust passive (vision based) terrain relative navigation based on two non-static cameras. Primary Technical Hurdles: #• Accurate time synchronization of distributed stereo system #• Real-time camera to camera pose estimation and on-board map construction #• Vibration and motion blur analysis for low altitude flight with wing-tip systems

## Anticipated Benefits

Airborne visual measurements could be used to enhance aircraft or spacecraft vehicle visual awareness, as well as a valuable tool during flight research.

## Primary U.S. Work Locations and Key Partners



Organizations Performing Work	Role	Type	Location
★Armstrong Flight Research Center(AFRC)	Lead Organization	NASA Center	Edwards, California
●Jet Propulsion Laboratory(JPL)	Supporting Organization	NASA Center	Pasadena, California



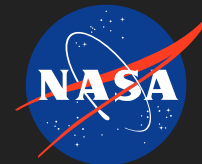
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### Primary U.S. Work Locations

California

### Project Transitions



**October 2017:** Project Start



**September 2018:** Closed out

**Closeout Summary:** We expect to complete two flights with the camera pods I n February 2019. This will enable JPL to take the initial data and make decisions about how to move forward with this innovation.

### Project Website:

[https://www.nasa.gov/directorates/spacetech/innovation\\_fund/index.html#.VC](https://www.nasa.gov/directorates/spacetech/innovation_fund/index.html#.VC)

### Organizational Responsibility

#### Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

#### Lead Center / Facility:

Armstrong Flight Research Center (AFRC)

#### Responsible Program:

Center Innovation Fund: AFRC CIF

### Project Management

#### Program Director:

Michael R Lapointe

#### Program Manager:

David F Voracek

#### Principal Investigators:

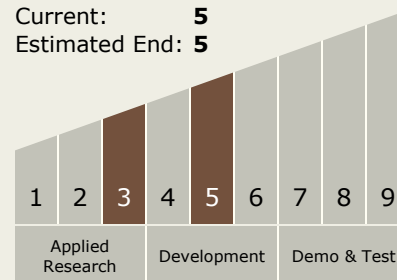
Matthew L Versteeg  
John Baca

### Technology Maturity (TRL)

Start: 3

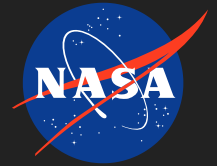
Current: 5

Estimated End: 5



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### Technology Areas

#### Primary:

- TX04 Robotic Systems
  - └ TX04.5 Autonomous Rendezvous and Docking
    - └ TX04.5.1 Relative Navigation Sensors

### Target Destinations

Earth, The Moon, Mars